

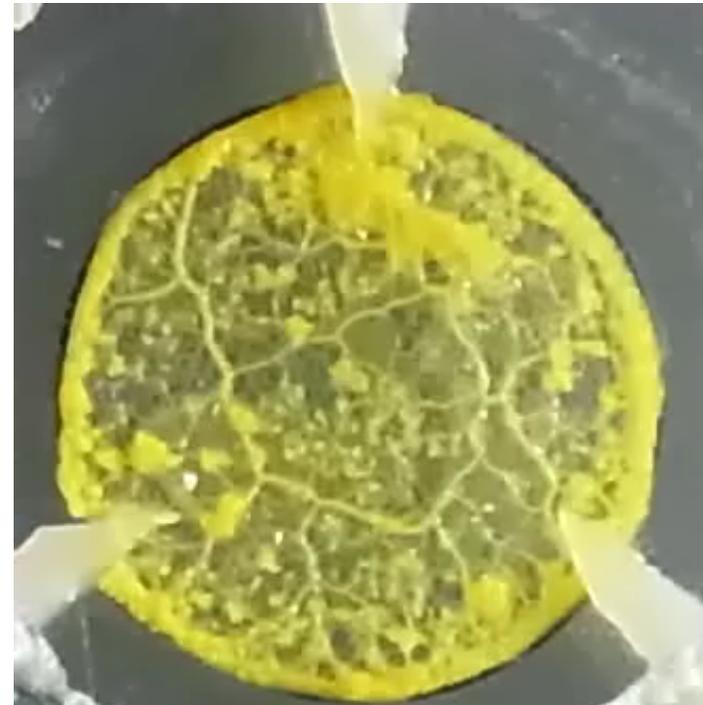
# Mathematical model for spreading *Physarum*

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Hiroshima University

# Plasmodium of true Slime mold

Unicellular organism containing multi nuclei

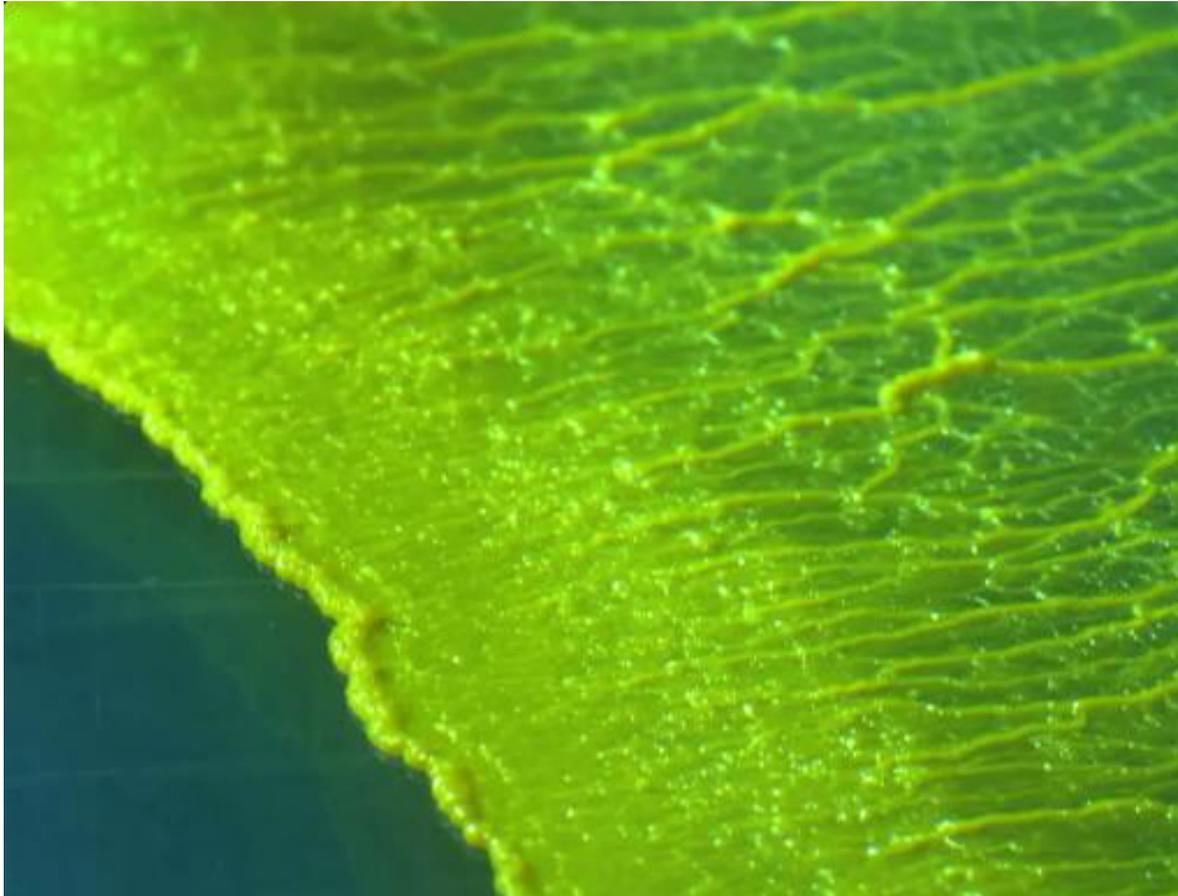


← 30mm →

No nervous system.

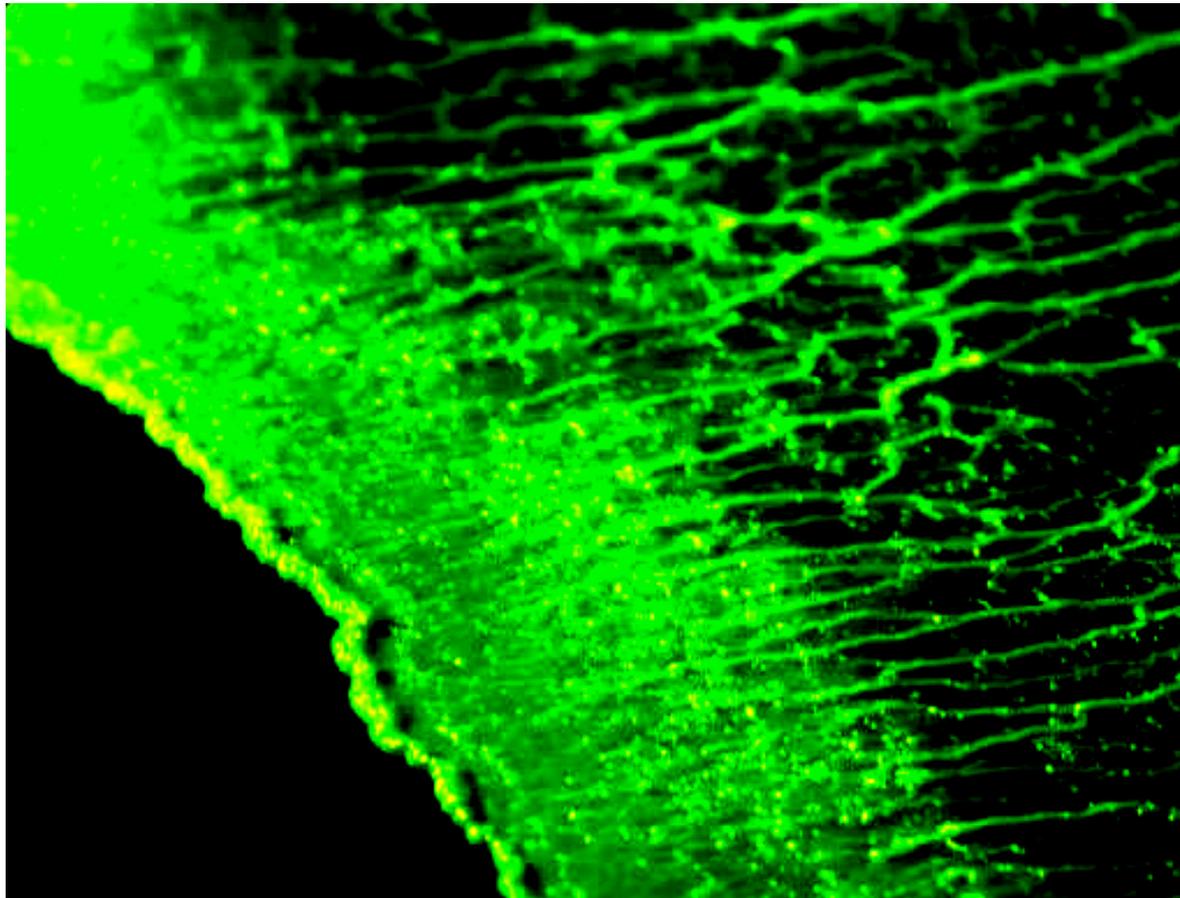
Local information processing + Mechanics

# Propagation of Slime mold



Thickness oscillation + Propagation

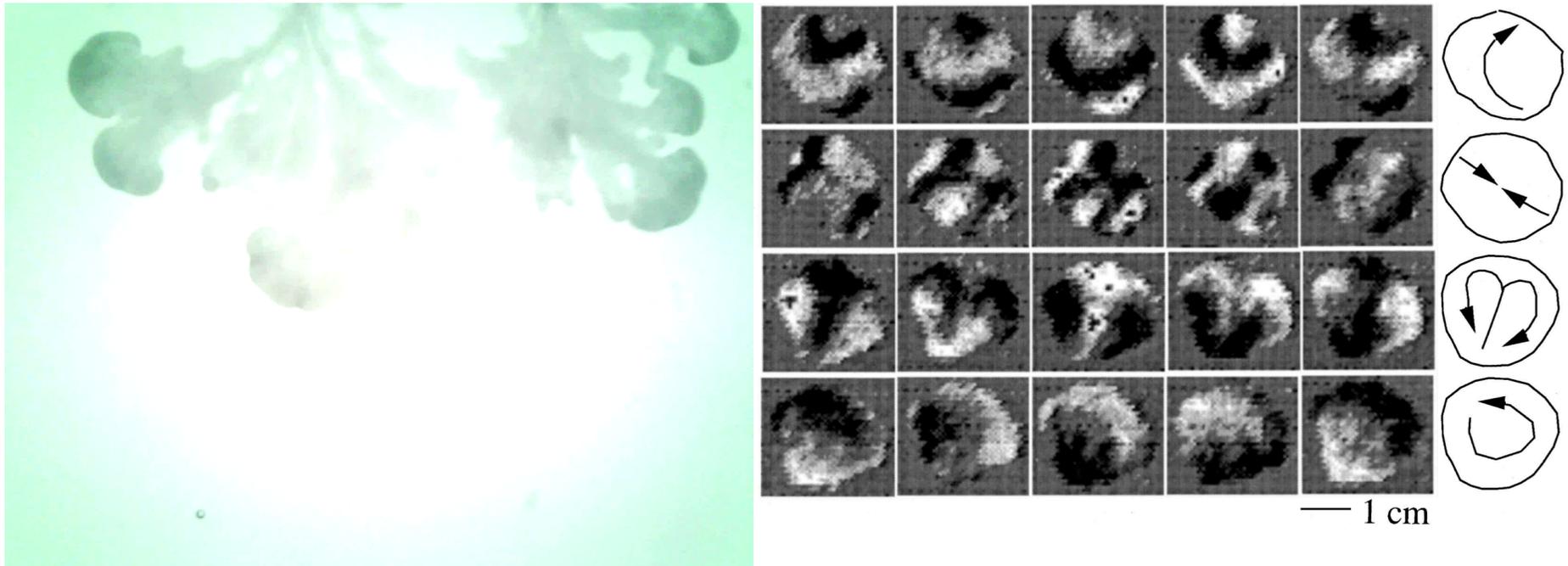
# Oscillation of slime mold



Thickness oscillation + Propagation

( x 60)

# Thickness oscillation



T.Nakagaki, et. al. Biophys. Chem. (2000)

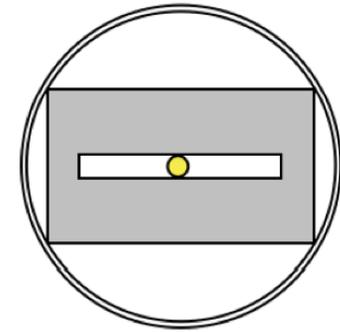
## Mathematical models

A. Tero, R. Kobayashi and T. Nakagaki, Physica D (2005)

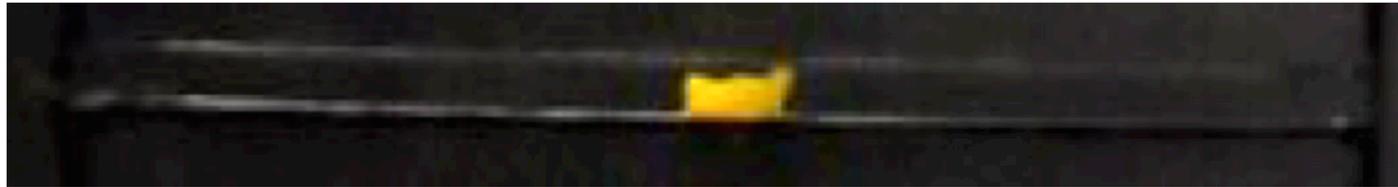
R. Kobayashi, A. Tero and T. Nakagaki, J. Theor. Biol. (2006)

K. Ueda, Phys. Rev. E. (2011)

## Two typical locomotion in a lane



Moving both side



One direction moving + ?

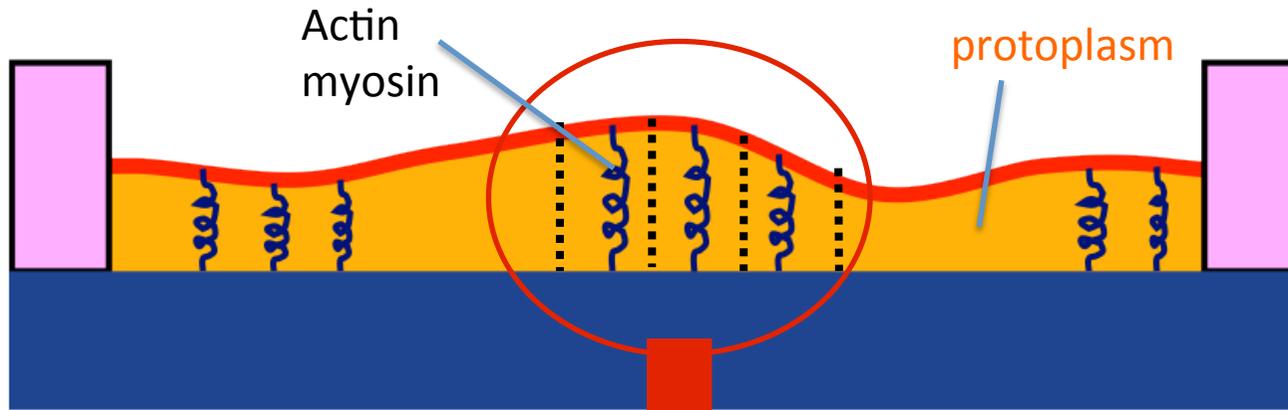


Question:

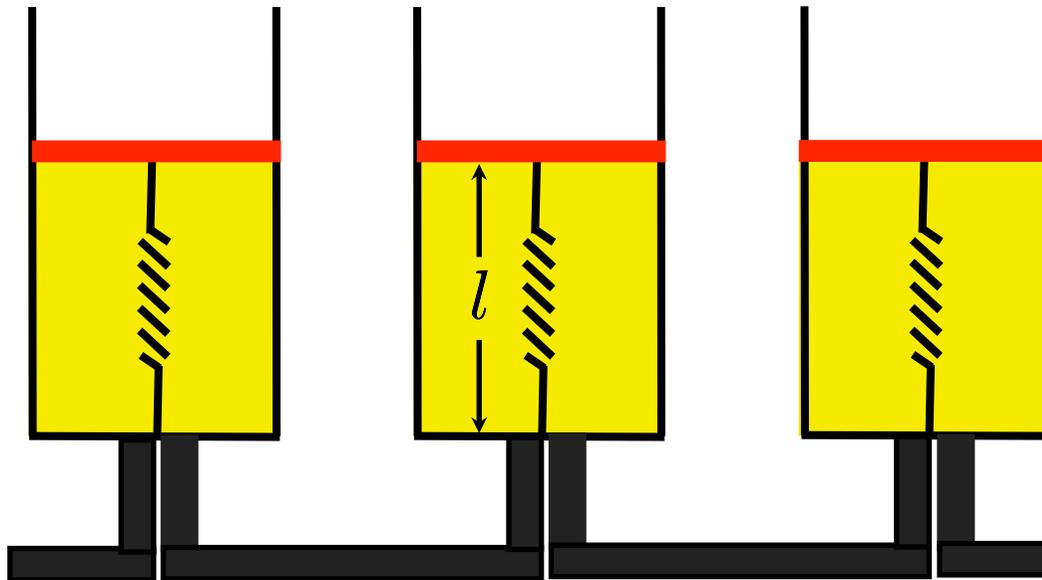
How do they know the edge, and turn to the direction?

# 1. Oscillation model

# Thickness oscillation



R. Kobayashi et al. (2006)



Spring coefficient

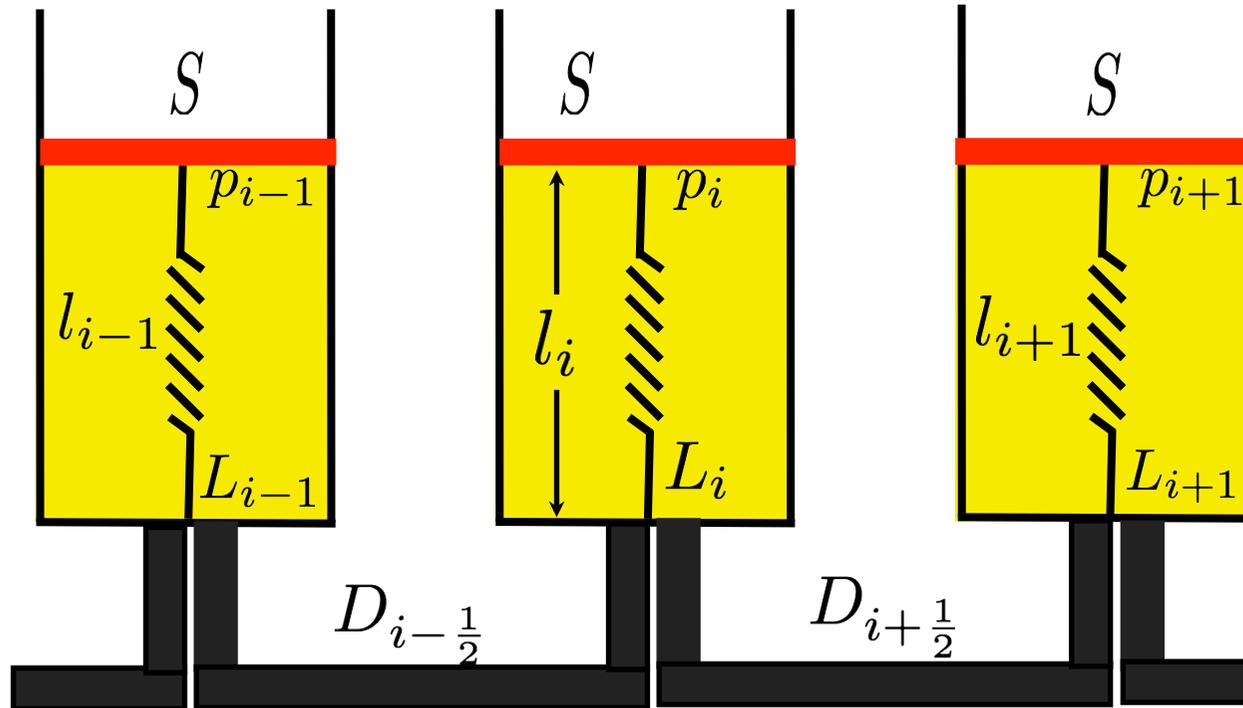
Natural length

$$T = \alpha(l - L)$$

$$= \frac{\kappa}{L}(l - L)$$

$$= \kappa\left(\frac{l}{L} - 1\right)$$

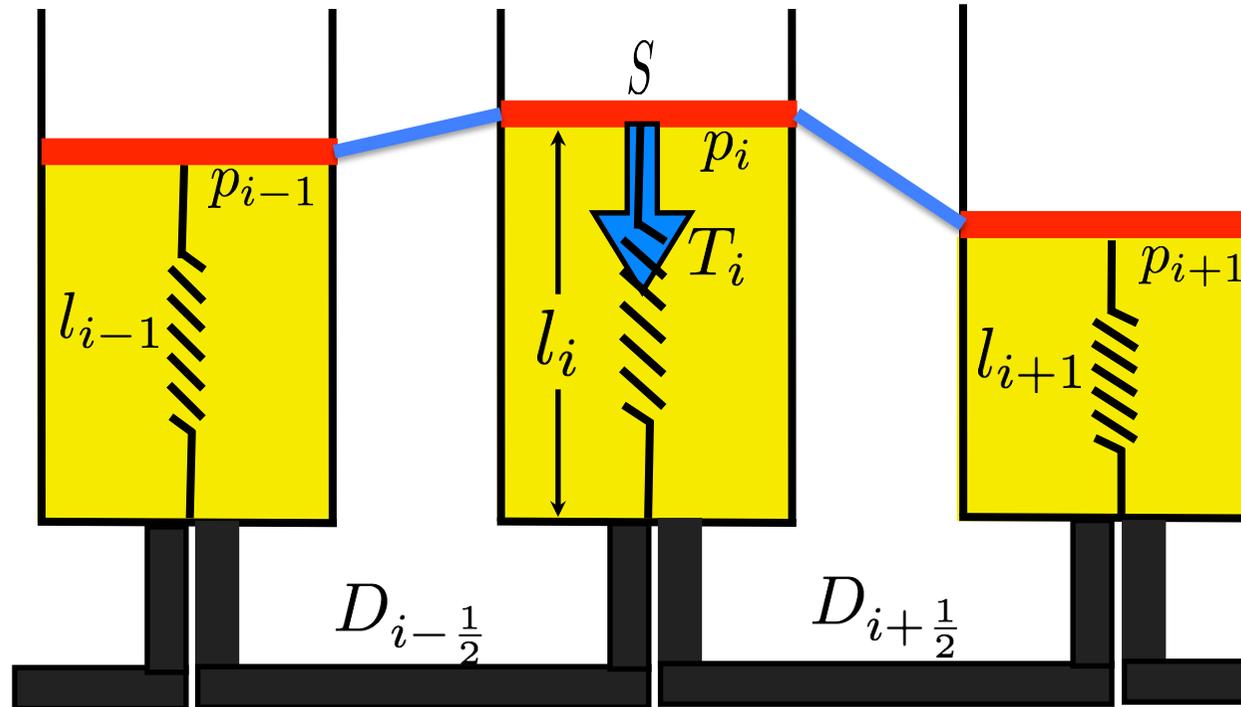
# Thickness oscillation model



Spring tension:  $T_i = \max\left\{\kappa_i \left(\frac{l_i}{L_i} - 1\right), 0\right\}$

Volume of protoplasm:  $S\dot{l}_i = D_{i-\frac{1}{2}}(p_{i-1} - p_i) + D_{i+\frac{1}{2}}(p_{i+1} - p_i)$

# Interaction between cylinder heads



$$Sp_i = T_i + \underbrace{k_{i+\frac{1}{2}}(l_i - l_{i+1}) + k_{i-\frac{1}{2}}(l_i - l_{i-1})}_{\text{Elastic film connecting among cylinder heads}}$$

Elastic film connecting among cylinder heads

# Dynamics of active spring

Natural length of spring  $i$ :

$$L_i = \bar{L}_i(1 + a \sin \phi_i)$$

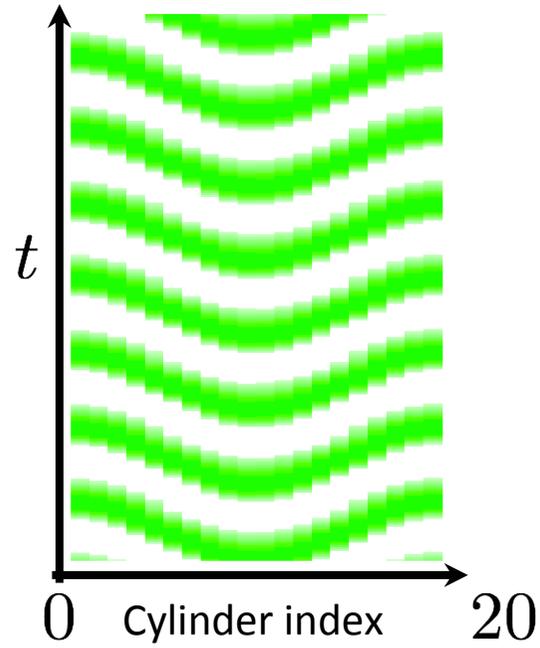
Phase dynamics:

$$\dot{\phi}_i = \omega + \frac{T_i \Gamma(\phi_i, l_i, \bar{L}_i)}{\bar{L}_i}$$

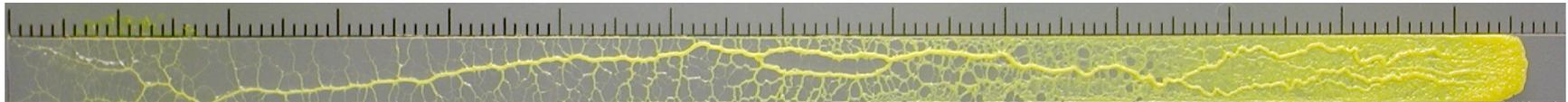
Phase modification term

$$\Gamma(\phi_i, l_i, \bar{L}_i) = \frac{\sigma a l_i \kappa_i}{\bar{L}_i (1 + a \sin \phi_i)^2} \cos \phi_i$$

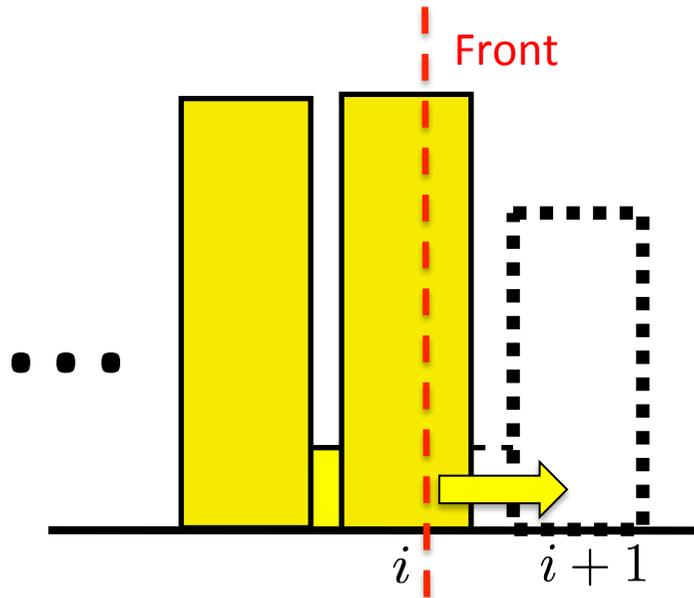
# Oscillation model



## 2. How to spread

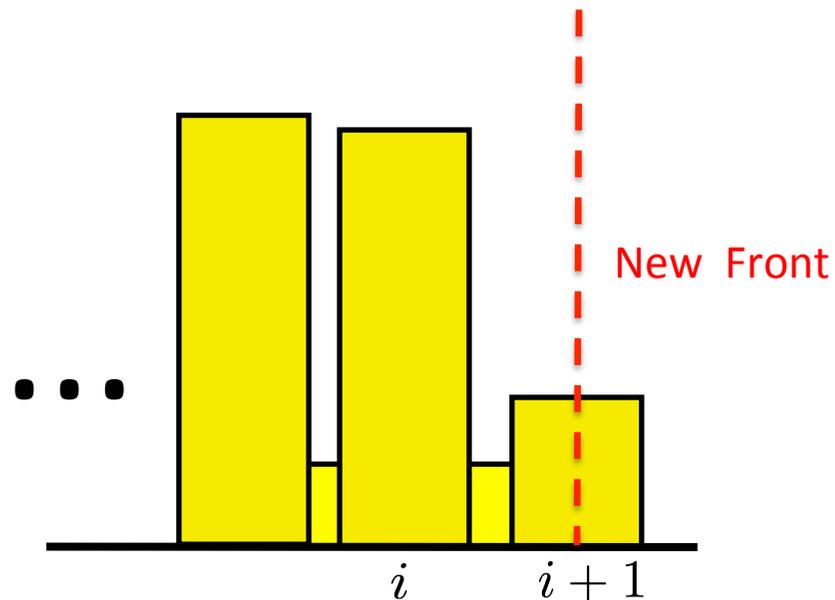


# How to move the boundary



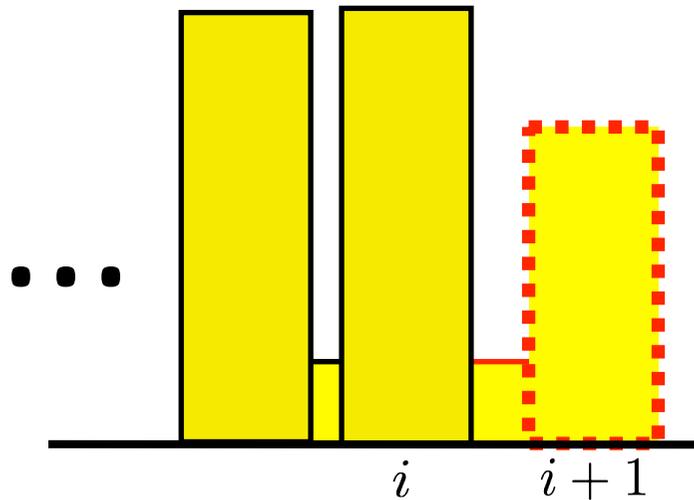
If pressure on boundary exceeds critical value

$$p_i > p_{th}(\eta_i) = \tilde{p}\eta_i$$



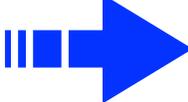
New cylinder appears!

# Gel degree



Gel degree  $\eta_i$  soft hard  
 ( $\eta_i : 0 \sim 1$ )

Condition of breakthrough the edge

  $p_i > p_{th}(\eta_i) = \tilde{p}\eta_i$

$\eta_{i+1} = \eta_{new} (= 0.3)$

Stiffness (strength) of actuator  $\kappa_i = \tilde{\kappa}\eta_i$

Stiffness of Membrane  $k_{i+\frac{1}{2}} = \tilde{k}\left(\frac{\eta_i + \eta_{i+1}}{2}\right)$

Conductivity  $D_{i+\frac{1}{2}} = \tilde{D}\left(\frac{\eta_i + \eta_{i+1}}{2}\right)^{-1}$

# Locomotion model

## Oscillation model

$$S\dot{l}_i = D_{i-\frac{1}{2}}(p_{i-1} - p_i) + D_{i+\frac{1}{2}}(p_{i+1} - p_i)$$
$$\dot{\phi}_i = \omega + T_i\Gamma(\phi_i, l_i, \bar{L}_i)$$

+

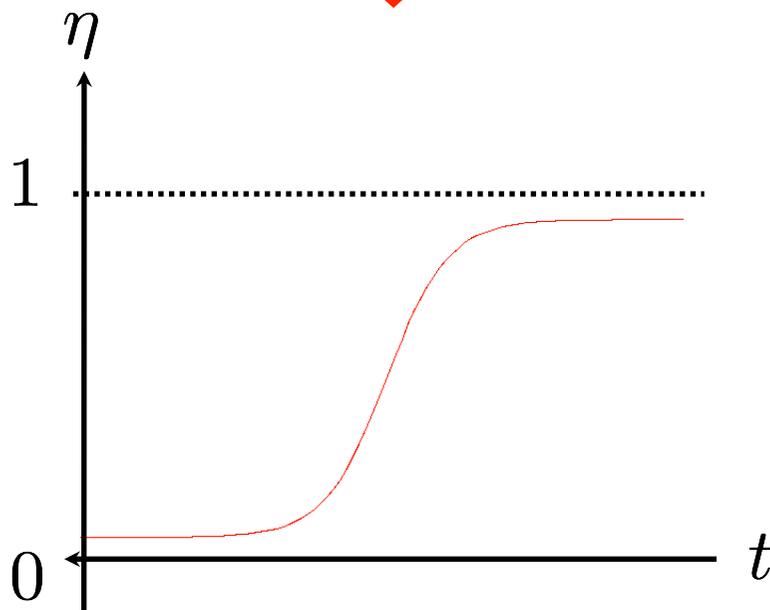
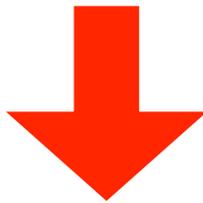
## Slow dynamics

$$\dot{\eta} = \epsilon_1(1 - \eta_i)\eta_i$$
$$\dot{\bar{L}}_i = \epsilon_2(l_i - \bar{L}_i) \quad \epsilon_1 = 0.02, \epsilon_2 = 0.01$$

# Slow dynamics

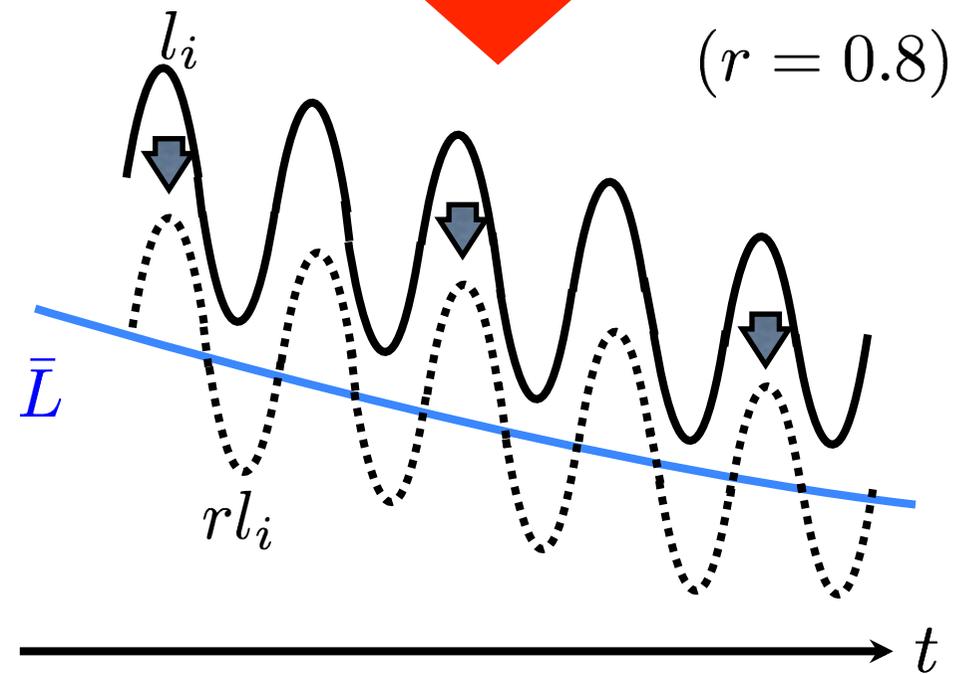
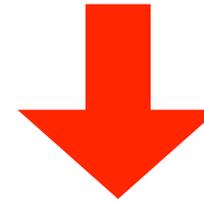
Gel degree

$$\dot{\eta}_i = \alpha(1 - \eta_i)\eta_i$$



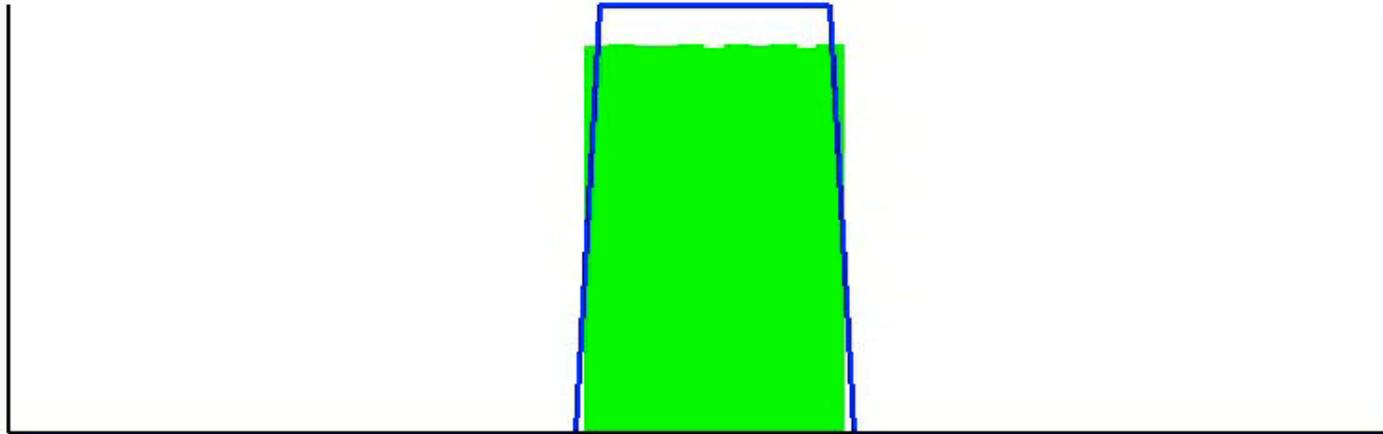
Adaptation of the center of oscillation

$$\dot{\bar{L}}_i = \epsilon(r l_i - \bar{L}_i)$$



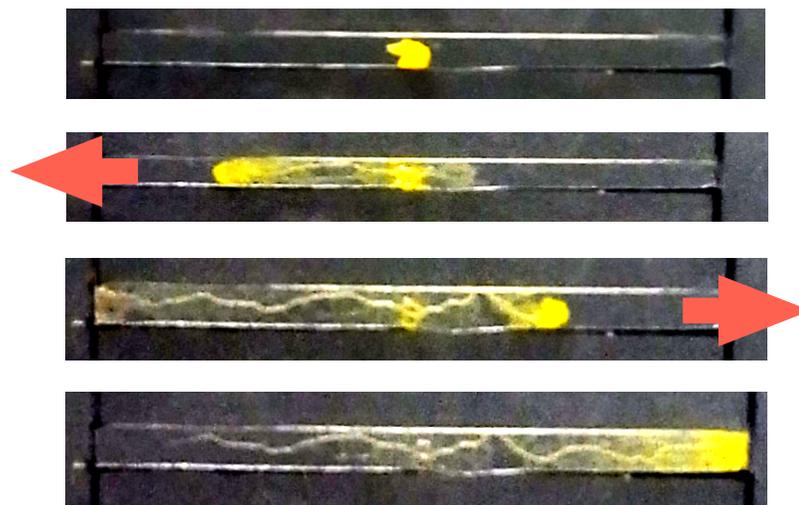
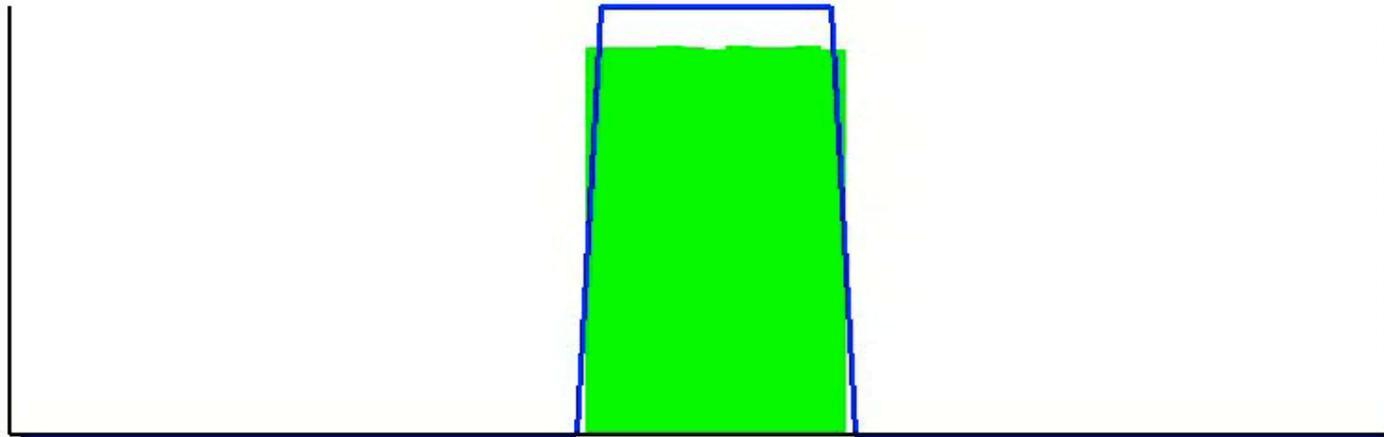
# Moving to both sides

$\eta$

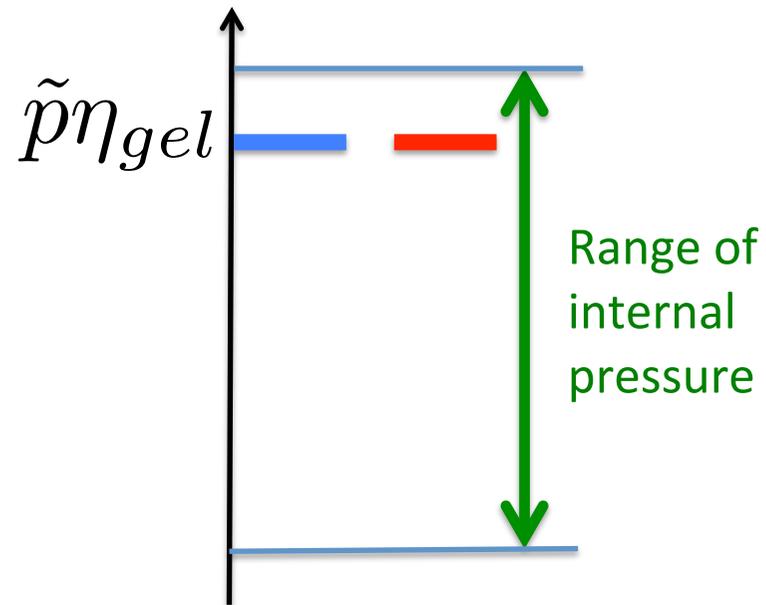
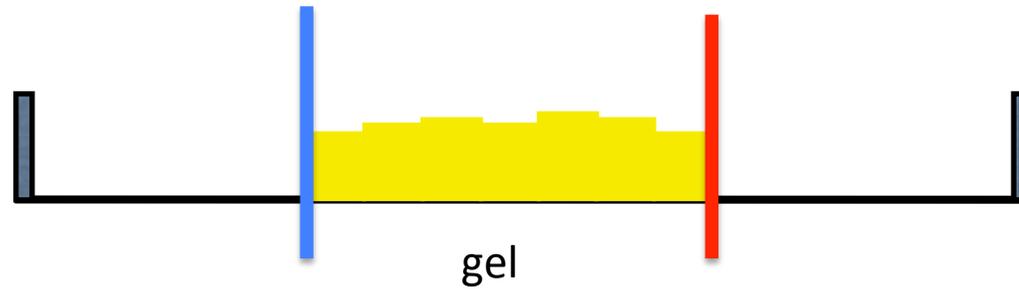


# One direction moving

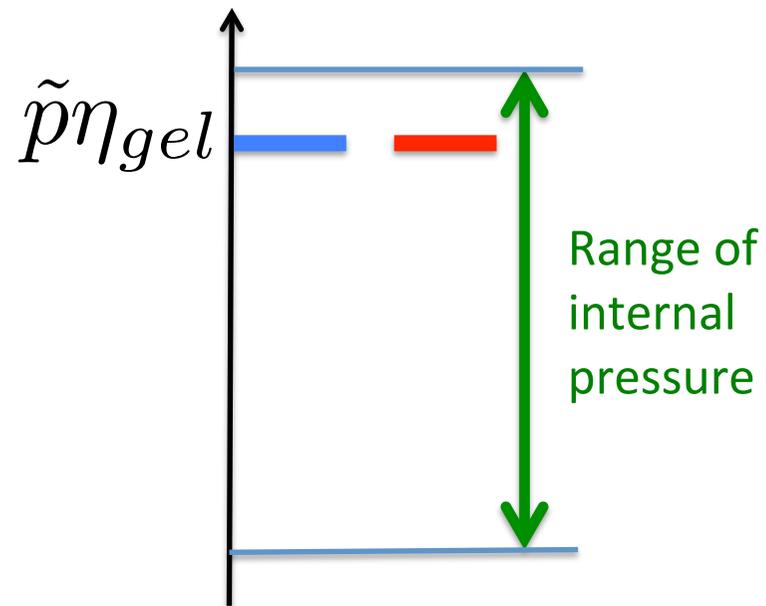
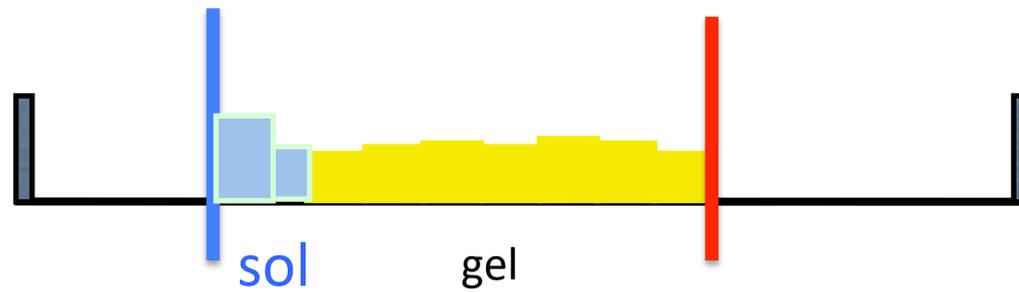
$\eta$



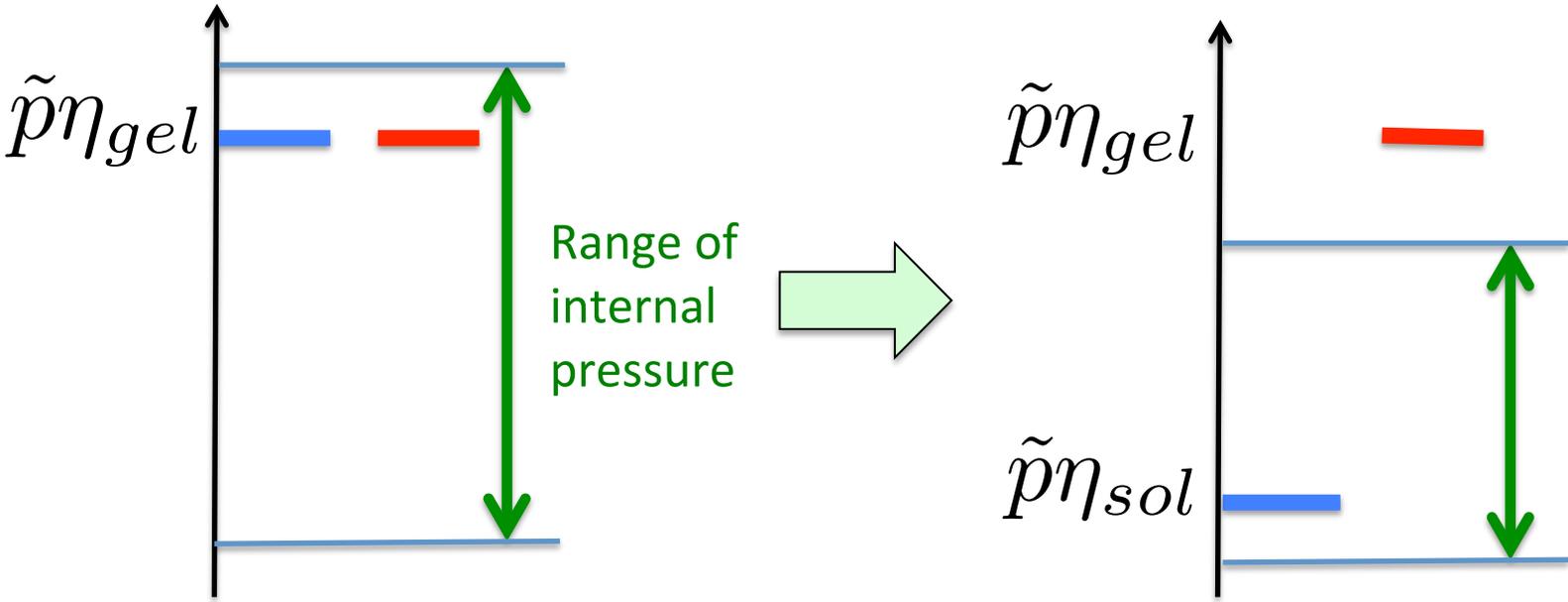
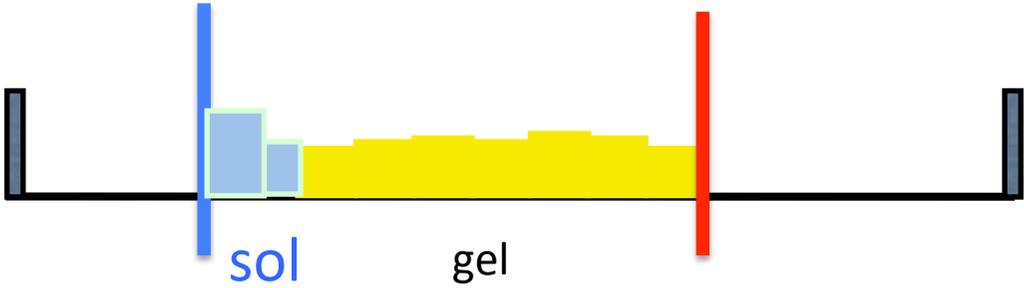
# How to move in the opposite direction



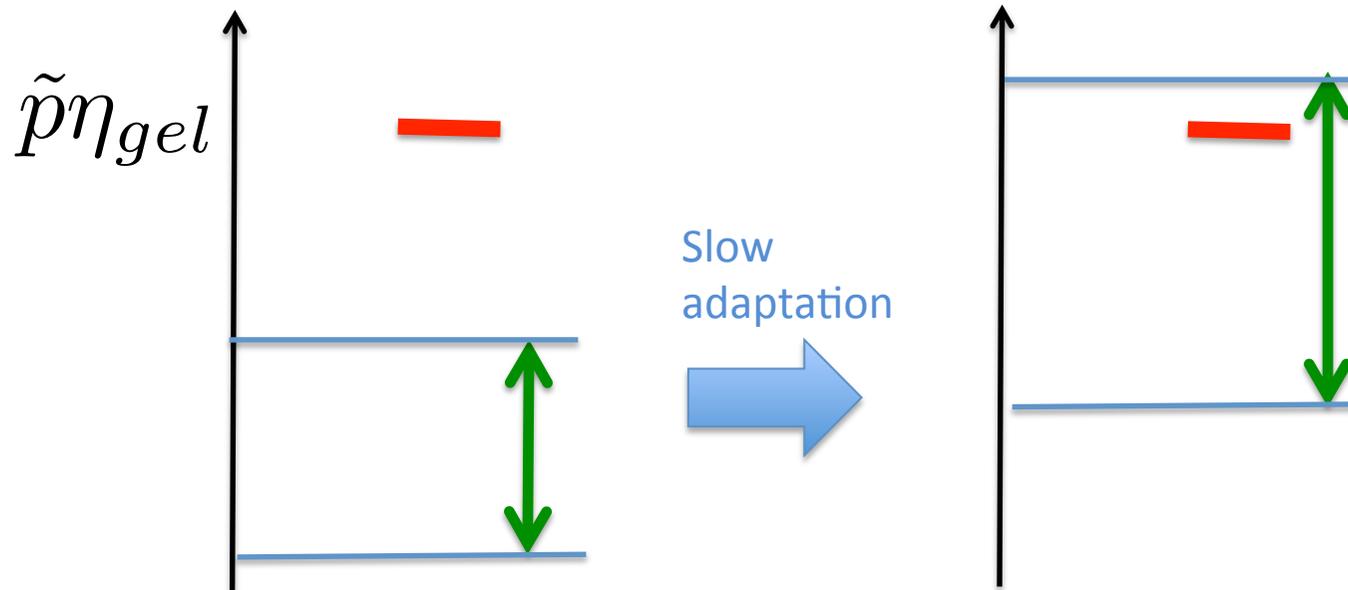
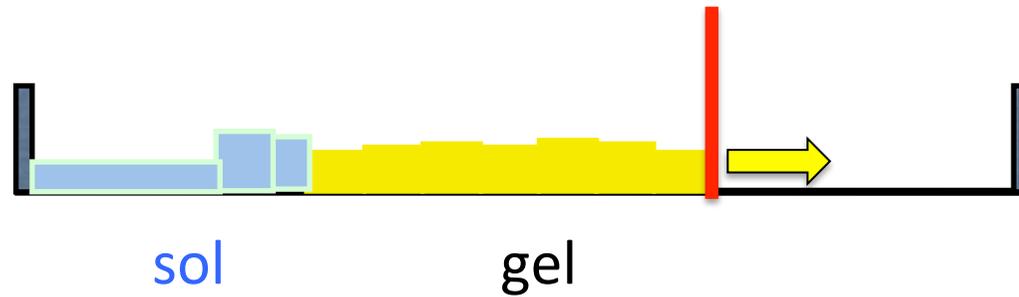
# How to move in the opposite direction



# How to move in the opposite direction



# After reaching one side

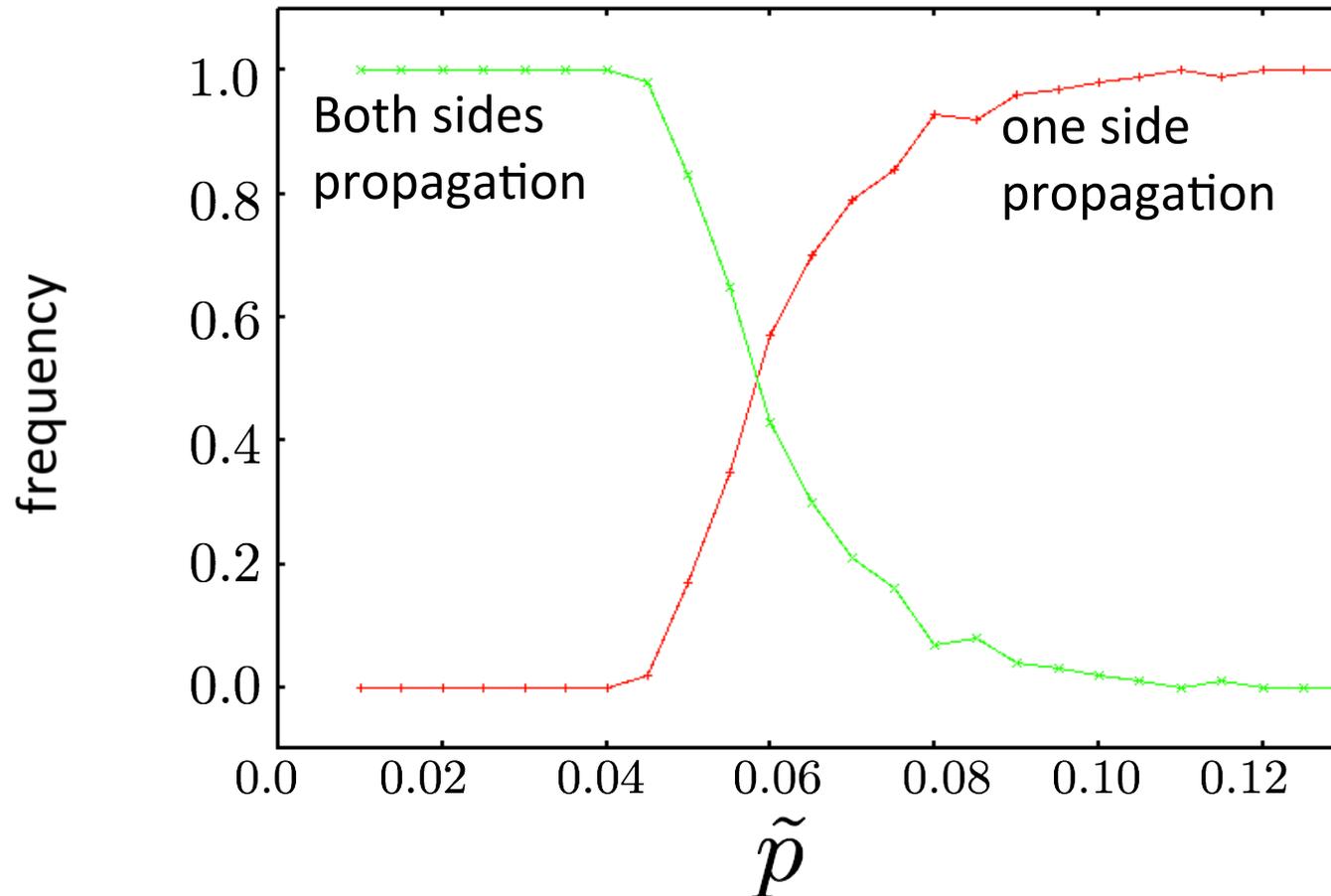


Slow dynamics induce pressure increasing.

# Our scenario

- Propagation causes decreasing of internal pressure.
- Slow dynamic, i.e. the transformation from sol to gel and the adaptation of natural length, induces increasing of internal pressure.

# Dependency of threshold parameter



Initial condition:

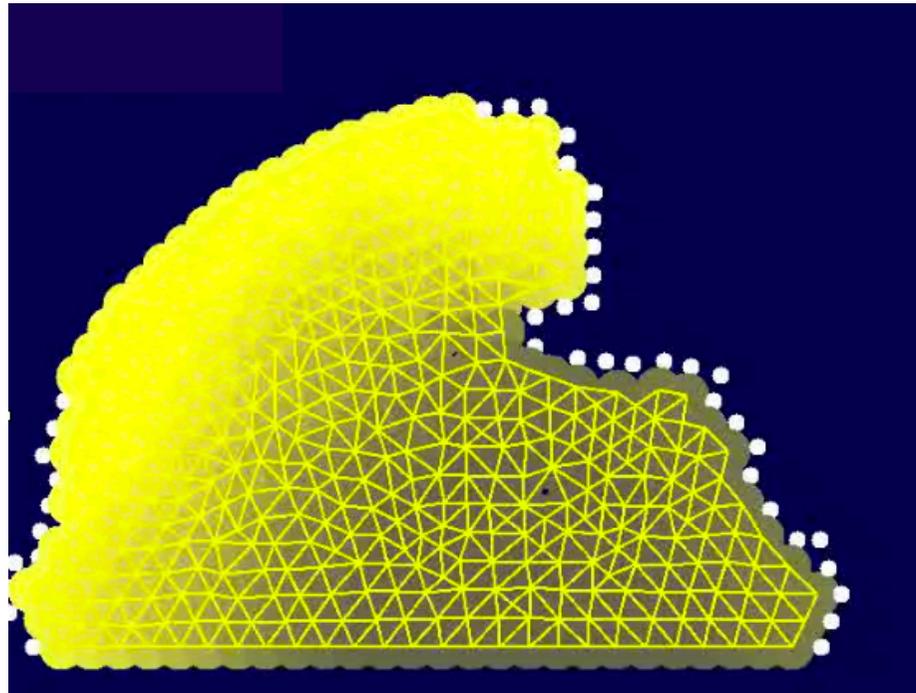
$l_i(0)$  : Uniform

$\theta_i(0)$  : Random

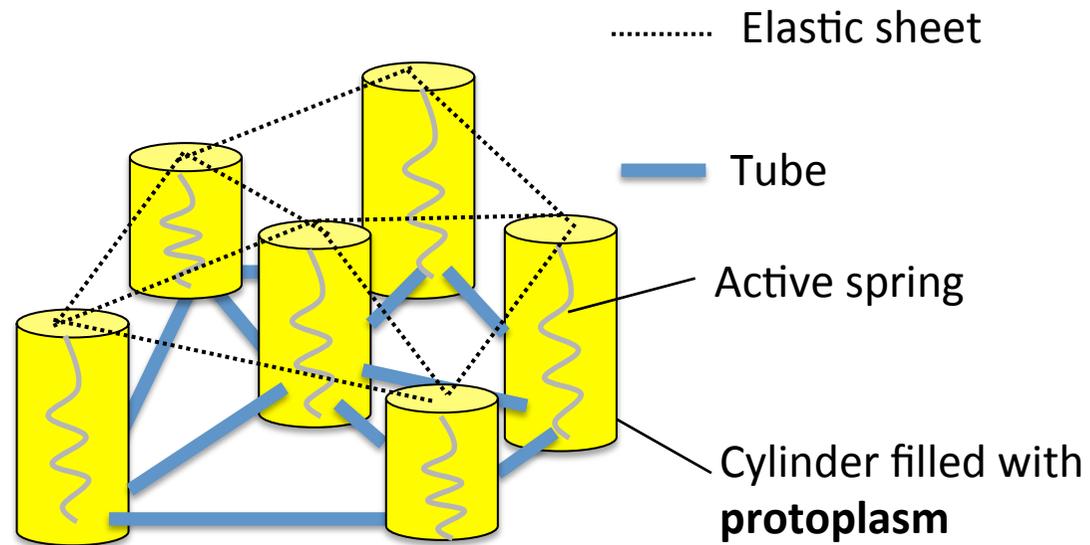
Condition for expand

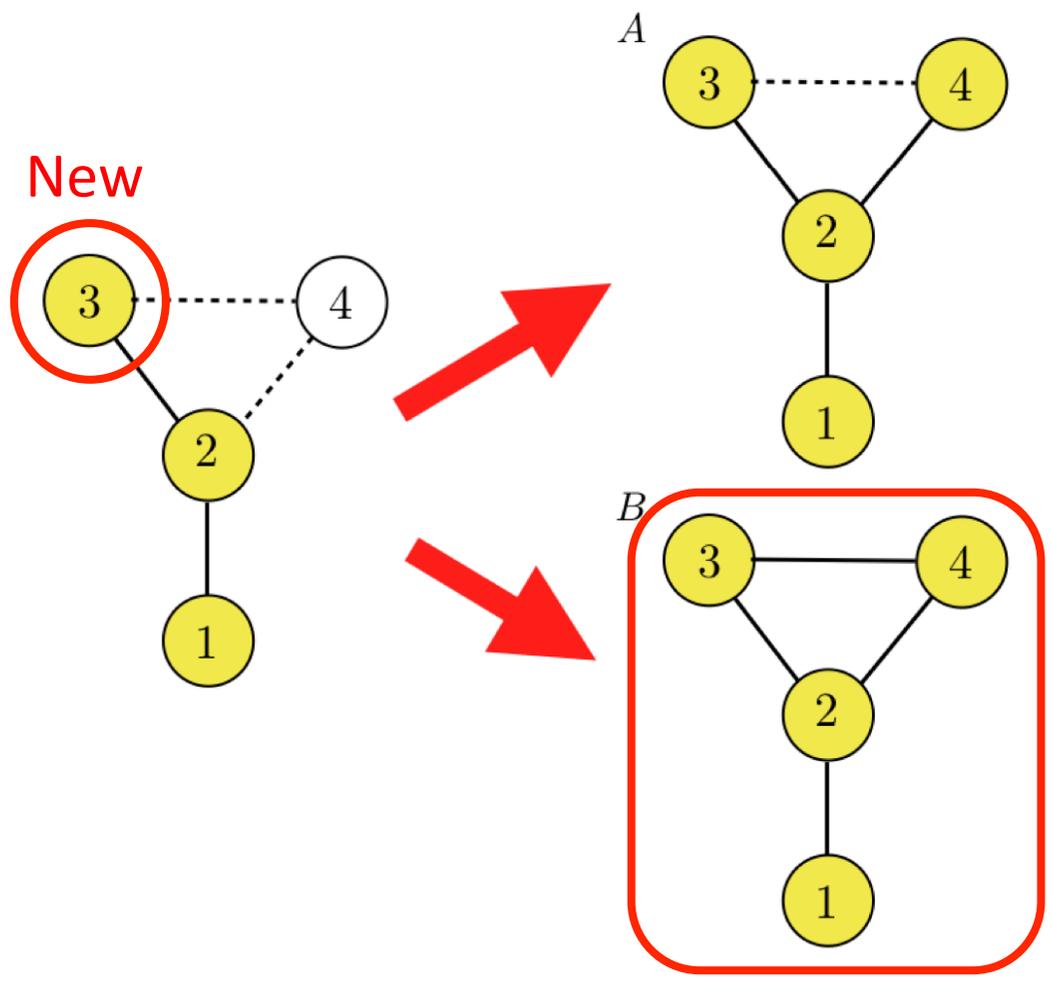
$$p_i > p_{th}(\eta_i) = \tilde{p}\eta_i$$

# 2D simulation



# 2D model

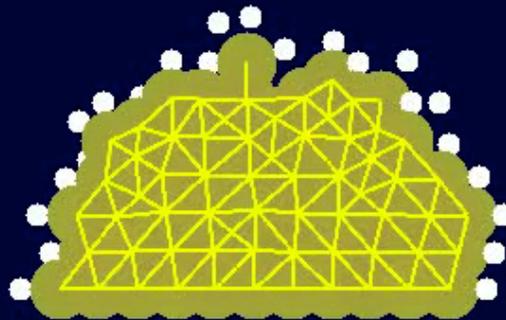




```
t=0.000000  
p_ave=0.03909694  
l_ave=2.00000000  
l_all=130.00000000  
cylinder=65  
counter=0
```

## Semicircular boundary

- Empty neighbor



# Conclusion

- We modeled pressure driven mathematical of physarum locomotion.
- Mechanism of the two types of propagation pattern can be explained with our model.
- Pressure